

ULTRADISCRETIZATION OF A SOLVABLE TWO-DIMENSIONAL CHAOTIC MAP ASSOCIATED WITH THE HESSE CUBIC CURVE

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Abstract

We present a solvable two-dimensional piecewise linear chaotic map which arises from the duplication map of a certain tropical cubic curve. Its general solution is constructed by means of the ultradiscrete theta function. We show that the map is derived by the ultradiscretization of the duplication map associated with the Hesse cubic curve. We also show that it is possible to obtain the nontrivial ultradiscrete limit of the solution in spite of a problem known as “the minus-sign problem.”

1 Introduction

Ultradiscretization [41] has been widely recognized as a powerful tool to extend the theory of integrable systems to the piecewise linear discrete dynamical systems (ultradiscrete systems) [7, 11, 23, 29, 31, 36, 37, 39, 44, 47, 50]. In particular, it yields various soliton cellular automata when it is possible to discretize the dependent variables into finite numbers of integers by a suitable choice of parameters. It has also established the links between the theory of integrable systems and various areas of mathematical sciences, such as combinatorics, representation theory, tropical geometry, traffic flow models, and so on [5, 6, 10, 13, 17, 19–22, 27, 30, 31, 33, 43, 45, 46, 49]. One of the key features of ultradiscretization is that one can obtain piecewise linear discrete dynamical systems from rational discrete dynamical systems by a certain limiting procedure, which corresponds to the low-temperature limit in the statistical mechanics. When this procedure is applied to a certain class of discrete integrable systems, wide classes of exact solutions, such as soliton solutions or periodic solutions, survive under the limit, which yield exact solutions to the ultradiscrete integrable systems.

While the application of ultradiscretization to the integrable systems has achieved a great success, it seems that only few results have been reported as to application to non-integrable systems [38, 40]. One reason may be that in many cases of non-integrable systems, fundamental properties are lost under the limit. For example, it is possible to ultradiscretize the celebrated logistic map formally, but however, its chaotic behavior is lost through the ultradiscretization [16].

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In [16], the ultradiscretization of a one-dimensional chaotic map which arises as the duplication formula of Jacobi's sn function has been considered. It exemplifies a *solvable chaotic system*, which is regarded as a dynamical system lying on the border of integrability and chaos [4], in the sense that though its exact solution is given by an elliptic function, however, its dynamics exhibits typical chaotic behaviors such as irreversibility, sensitivity to the initial values, positive entropy, and so on. By applying the ultradiscretization, it has been shown that we obtain the tent map and its general solution simultaneously. Moreover, a tropical geometric interpretation of the tent map has been presented, namely, it arises as the duplication map on a certain tropical biquadratic curve. This result implies that there is the world of elliptic curves and elliptic functions behind the tent map, which might be an unexpected and interesting viewpoint. It also suggests that the tropical geometry and the ultradiscretization provides a theoretical framework for the description of such a geometric aspect.

In this paper, we present two kinds of two-dimensional solvable chaotic maps and their general solutions that are directly connected through the ultradiscretization. In Section 2, we construct a piecewise linear map from a duplication map on a certain tropical plane cubic curve. We also construct its general solution in terms of the ultradiscrete theta function [16, 20, 26, 32, 33, 42] by using the tropical Abel–Jacobi map. In Section 3, we consider a certain rational map which arises as a duplication map on the Hesse cubic curve (see, for example, [1, 15, 35]), whose general solution is expressible in terms of the theta functions of level 3. In Section 4, we discuss the ultradiscretization of the rational map and its solution obtained in Section 3, and show that they yield the piecewise linear map and its solution obtained in Section 2. The rational map and its general solutions discussed in Section 3 and 4 involve a problem known as “the minus-sign problem,” which is usually regarded as an obstacle to successful application of the ultradiscretization. We show that it is possible to overcome the problem by taking careful parametrization and limiting procedure.

2 Duplication map on tropical cubic curve

2.1 Duplication map

In this section, we construct the duplication map on a certain tropical curve. For basic notions of the tropical geometry, we refer to [3, 12, 24–26, 34].

Let us consider the tropical curve C_K given by the tropical polynomial

$$\Psi(X, Y; K) = \max [3X, 3Y, X + Y + K, 0], \quad X, Y, K \in \mathbb{R}, \quad K > 0. \quad (2.1)$$

The curve C_K is defined as the set of points where Ψ is not differentiable. As shown in Fig.1(a), the vertices V_i and the edges E_i of C_K are given by $V_1 = (-K, 0)$, $V_2 = (0, -K)$, $V_3 = (K, K)$ and $E_1 = V_1V_2$, $E_2 = V_2V_3$, $E_3 = V_3V_1$, respectively. From the Newton subdivision of the support of C_K given in Fig.1(b), we see that C_K is a degree 3 curve. For a vertex on the tropical curve, let $\mathbf{v}_i \in \mathbb{Z}^2$ ($i = 1, \dots, n$) be the primitive tangent vectors along the edges emanating from the vertex. Then it is known that for any vertex there exist natural numbers $w_i \in \mathbb{Z}_{>0}$ ($i = 1, \dots, n$) such that the following balancing condition holds:

$$w_1\mathbf{v}_1 + \dots + w_n\mathbf{v}_n = (0, 0). \quad (2.2)$$

We call w_i the weight of corresponding edge. Now, since the primitive tangent vectors emanating from V_1 is given by $(-1, 0)$, $(1, -1)$ and $(2, 1)$, the balancing condition at V_1 is given by

$$3(-1, 0) + (1, -1) + (2, 1) = (0, 0). \quad (2.3)$$

Therefore, the weight of E_1 , E_3 and the tentacle along the edges emanating from V_1 are given by 1, 1 and 3, respectively. The balancing condition at V_2 and V_3 shows that the weight of the edges E_i ($i = 1, 2, 3$) are 1, and those of tentacles of C_K are all 3, respectively. If a vertex V is 3-valent, namely V has exactly three adjacent edges whose primitive tangent vectors and weights are \mathbf{v}_i and w_i ($i = 1, 2, 3$), respectively, the multiplicity of V is defined by $w_1 w_2 |\det(\mathbf{v}_1, \mathbf{v}_2)| = w_2 w_3 |\det(\mathbf{v}_2, \mathbf{v}_3)| = w_3 w_1 |\det(\mathbf{v}_3, \mathbf{v}_1)|$. If all the vertices of the tropical curve are 3-valent and have multiplicity 1, then the curve is said to be smooth. The multiplicity of the vertex V_1 is computed as

$$3 \cdot 1 \cdot \left| \det \begin{pmatrix} -1 & 0 \\ 1 & -1 \end{pmatrix} \right| = 3, \quad (2.4)$$

and similarly those of V_2 and V_3 are both 3, which imply that C_K is not smooth. The genus is equal to the first Betti number of C_K , which is 1 as shown in Fig.1(a). Thus the curve C_K is a non-smooth, degree 3 tropical curve of genus 1. Note that the cycle \overline{C}_K of C_K (the triangle obtained by removing the tentacles from C_K) can be given by the equation

$$\max[3X, 3Y, 0] = X + Y + K. \quad (2.5)$$

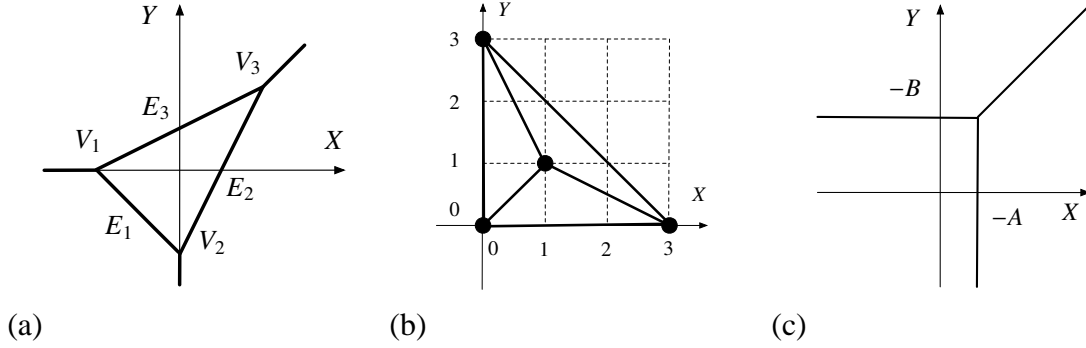


Figure 1. (a): Tropical curve C_K . $V_1 = (-K, 0)$, $V_2 = (0, -K)$, $V_3 = (K, K)$. Primitive tangent vector of each edge: E_1 : $\mathbf{v}_1 = (1, -1)$, E_2 : $\mathbf{v}_2 = (1, 2)$, E_3 : $\mathbf{v}_3 = (2, 1)$. (b): Newton subdivision of the support of C_K . (c): Tropical line.

A tropical line is the tropical curve given by the tropical polynomial of the form

$$L(X, Y) = \max[X + A, Y + B, 0], \quad (2.6)$$

which is shown in Fig.1 (c). The three primitive tangent vectors emanating from the vertex are given by $(-1, 0)$, $(0, -1)$, $(1, 1)$. From the balancing condition $(-1, 0) + (0, -1) + (1, 1) = (0, 0)$, the weight of edges are all 1.

Vigeland [48] has introduced the group law on the tropical elliptic curve, which is a smooth, degree 3 curve of genus 1. According to the group law, the duplication map is formulated as

follows; let C be a tropical elliptic curve and let \overline{C} be its cycle. Take a point $P \in \overline{C}$. We draw a tropical line that intersects with \overline{C} at P with the intersection multiplicity 2, and denote the other intersection point by $P * P$. Drawing a tropical line passing through O and $P * P$ with a suitable choice of the origin of addition $O \in \overline{C}$, the third intersection point is $2P$.

For a given point P on a tropical elliptic curve, the tropical line that intersects at P with the intersection multiplicity 2 does not exist in general. However, the curve C_K has a remarkable property that it is possible to draw a tropical line that intersects at any point on \overline{C}_K with the intersection multiplicity 2. The explicit form of the duplication map is given as follows:

Proposition 2.1 *Choosing the origin as $O = V_3$, the duplication map $\overline{C}_K \ni P = (X, Y) \mapsto 2P = (\overline{X}, \overline{Y}) \in \overline{C}_K$ on the tropical cubic curve C_K is given by*

$$\overline{X} = Y + 3 \max[0, X] - 3 \max[X, Y], \quad \overline{Y} = X + 3 \max[0, Y] - 3 \max[X, Y], \quad (2.7)$$

or

$$X_{n+1} = Y_n + 3 \max[0, X_n] - 3 \max[X_n, Y_n], \quad Y_{n+1} = X_n + 3 \max[0, Y_n] - 3 \max[X_n, Y_n], \quad (2.8)$$

where (X_n, Y_n) is the point obtained by the n times successive applications of the map to (X, Y) .

Proof.

Case 1: $P \in E_1$ As illustrated in Fig.2(a), the primitive tangent vectors of the two edges passing through P are $(1, -1)$ (thick line) and $(1, 1)$ (broken line), respectively, and the weight of the edges crossing at P are both 1. Then the intersection multiplicity is given by

$$1 \cdot 1 \cdot \left| \det \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \right| = 2. \quad (2.9)$$

Let $P * P$ be the other intersection point. Note that the intersection multiplicity at $P * P$ is 1. Then the map $P = (X, Y) \mapsto P * P = (X', Y')$ is constructed as follows. Since $P \in E_1$ and $P * P \in E_1 \cup E_2$, we have

$$0 = X + Y + K, \quad \max[3X', 3Y'] = X' + Y' + K. \quad (2.10)$$

Subtracting the second equation from the first one, we obtain by using $(X - X')/(Y - Y') = 1$

$$X' = X - 3 \max[X, Y], \quad Y' = Y - 3 \max[X, Y]. \quad (2.11)$$

Our choice of the origin of addition $O = V_3$ makes the form of $2P$ simple. It is obvious as illustrated in Fig.2 (b), that $2P = (\overline{X}, \overline{Y})$ is given by $(\overline{X}, \overline{Y}) = (Y', X')$. Hence we obtain the map $P \mapsto 2P$ as

$$\overline{X} = Y - 3 \max[X, Y], \quad \overline{Y} = X - 3 \max[X, Y], \quad (X, Y) \in E_1. \quad (2.12)$$

Case 2: $P \in E_2$ As illustrated in Fig.3(a), the two primitive tangent vectors of the edges passing through P are $(1, 2)$ and $(1, 0)$, and the weight of the edges crossing at P are both 1. Then the intersection multiplicity is given by

$$1 \cdot 1 \cdot \left| \det \begin{pmatrix} 1 & 2 \\ 1 & 0 \end{pmatrix} \right| = 2. \quad (2.13)$$

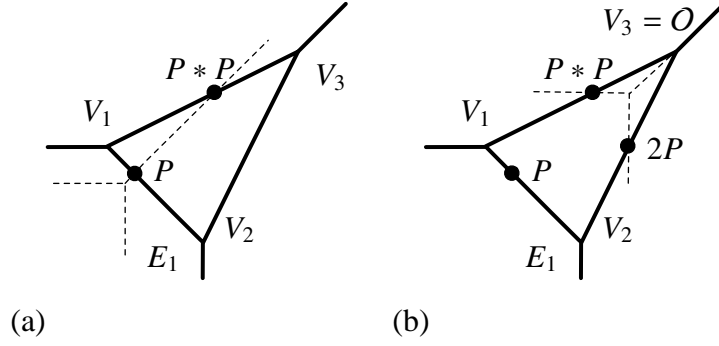


Figure 2. (a): Map $P \mapsto P * P$ for $P \in E_1$. The intersection point of C_K and the line passing through P with multiplicity 2 (broken line) is $P * P$. (b): Map $P * P \mapsto 2P$. The intersection point of C_K and the line passing through $O = V_3$ and $P * P$ (broken line) is $2P$. Obviously $P * P$ and $2P$ are symmetric with respect to $X = Y$.

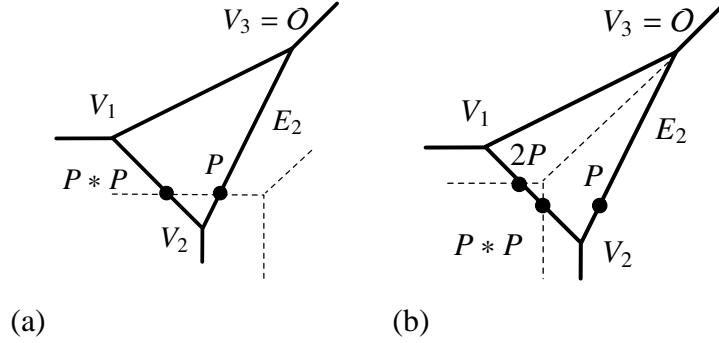


Figure 3. (a): Map $P \mapsto P * P$ for $P \in E_2$. (b): Map $P * P \mapsto 2P$.

Since $P \in E_2$ and $P * P \in E_1 \cup E_3$, we have

$$3X = X + Y + K, \quad \max[3Y', 0] = X' + Y' + K. \quad (2.14)$$

By using $Y' = Y$, we obtain the map $P \mapsto P * P$ and $P \mapsto 2P$ as

$$X' = -2X + 3 \max[0, Y], \quad Y' = Y, \quad (2.15)$$

$$\bar{X} = Y, \quad \bar{Y} = -2X + 3 \max[0, Y], \quad (X, Y) \in E_2, \quad (2.16)$$

respectively.

Case 3: $P \in E_3$ As illustrated in Fig.4(a), the two primitive tangent vectors of the edges passing through P are $(2, 1)$ and $(0, 1)$, and the weight of the edges crossing at P are both 1. The intersection multiplicity is given by

$$1 \cdot 1 \cdot \left| \det \begin{pmatrix} 2 & 1 \\ 0 & 1 \end{pmatrix} \right| = 2. \quad (2.17)$$

Since $P \in E_3$ and $P * P \in E_1 \cup E_2$, we have

$$3Y = X + Y + K, \quad \max[3X', 0] = X' + Y' + K. \quad (2.18)$$

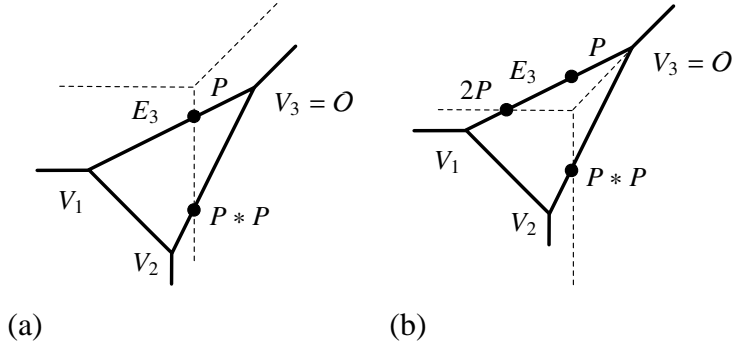


Figure 4. (a): Map $P \mapsto P * P$ for $P \in E_3$. (b): Map $P * P \mapsto 2P$.

By using $X' = X$, we obtain the map $P \mapsto P * P$ and $P \mapsto 2P$ as

$$X' = X, \quad Y' = -2Y + 3 \max[0, X], \quad (2.19)$$

$$\bar{X} = -2Y + 3 \max[0, X], \quad \bar{Y} = X, \quad (X, Y) \in E_3, \quad (2.20)$$

respectively.

We finally obtain eq. (2.7) by collecting eqs. (2.12), (2.16) and (2.20) together. \square

Strictly speaking, the group law in [48] cannot be applied to our case, since C_K is not a smooth curve. However, it is possible to show by direct computation that the map (2.8) is actually a duplication map on the tropical Jacobian of \bar{C}_K . For this purpose, we first compute the total lattice length \mathcal{L} of \bar{C}_K , which is defined by the sum of the length of each edge scaled by the norm of corresponding primitive tangent vector:

$$\mathcal{L} = \sum_{i=1}^3 \frac{|E_i|}{|v_i|} = \frac{\sqrt{5}K}{\sqrt{5}} + \frac{\sqrt{2}K}{\sqrt{2}} + \frac{\sqrt{5}K}{\sqrt{5}} = 3K. \quad (2.21)$$

Then the tropical Jacobian $J(\bar{C}_K)$ of \bar{C}_K is given by

$$J(\bar{C}_K) = \mathbb{R}/\mathcal{L}\mathbb{Z} = \mathbb{R}/3K\mathbb{Z}. \quad (2.22)$$

The Abel–Jacobi map $\eta : \bar{C}_K \rightarrow J(\bar{C}_K)$ is defined as the piecewise linear map satisfying

$$\eta(O) = \eta(V_3) = 0, \quad \eta(V_1) = \frac{|E_3|}{|v_3|} = K, \quad \eta(V_2) = \eta(V_1) + \frac{|E_2|}{|v_2|} = 2K. \quad (2.23)$$

Proposition 2.2 *The map $\bar{C}_K \ni P = (X, Y) \mapsto \bar{P} = (\bar{X}, \bar{Y}) \in \bar{C}_K$ defined by eq. (2.7) is a duplication map on the Jacobian $J(\bar{C}_K)$. Namely, we have $\eta(\bar{P}) = 2\eta(P) \pmod{3K}$.*

Proof. We consider the case $P \in E_1$. Suppose $P = (X, Y)$ satisfies $V_1P : V_2P = s : 1 - s$ ($0 \leq s \leq 1$), namely

$$P = (X, Y) = (-(1 - s)K, -sK), \quad \eta(P) = \eta(V_1) + sK = (1 + s)K. \quad (2.24)$$

Case (I): $X \leq Y$ ($0 \leq s \leq \frac{1}{2}$). From eq. (2.12), \bar{P} is given by

$$\bar{X} = Y - 3Y = -2Y = 2sK, \quad \bar{Y} = X - 3Y = (-1 + 4s)K, \quad \bar{P} \in E_2, \quad (2.25)$$

which implies

$$V_2\bar{P} : V_3\bar{P} = 2s : 1 - 2s, \quad \eta(\bar{P}) = \eta(V_2) + 2sK = 2(1 + s)K = 2\eta(P). \quad (2.26)$$

Case (II): $X \geq Y$ ($\frac{1}{2} \leq s \leq 1$). In this case, \bar{P} is given by

$$\bar{X} = Y - 3X = (3 - 4s)K, \quad \bar{Y} = -2X = 2(1 - s)K, \quad \bar{P} \in E_3, \quad (2.27)$$

which implies

$$V_3\bar{P} : V_1\bar{P} = -1 + 2s : 2(1 - s), \quad \eta(\bar{P}) = (-1 + 2s)K \equiv 2(1 + s)K = 2\eta(P) \pmod{3K}. \quad (2.28)$$

Therefore we have shown that $\eta(\bar{P}) = 2\eta(P)$ for $P \in E_1$. We omit the proof of other cases since they can be shown in a similar manner. \square

2.2 General solution

From the construction of the map (2.8), it is possible to obtain the general solution by using the Abel-Jacobi map of \bar{C}_K . Let π_1 and π_2 be projections from \bar{C}_K to the X -axis and the Y -axis, respectively. Then the maps $\pi_1 \circ \eta^{-1}$ and $\pi_2 \circ \eta^{-1}$, namely, the maps from the tropical Jacobian to the X -axis and the Y -axis through the Abel-Jacobi map are given as illustrated in Fig. 5(a) and (b), respectively. Therefore, Proposition 2.2 implies that $X_n = \pi_1 \circ \eta^{-1}(2^n u_0)$, $Y_n = \pi_2 \circ \eta^{-1}(2^n u_0)$ for

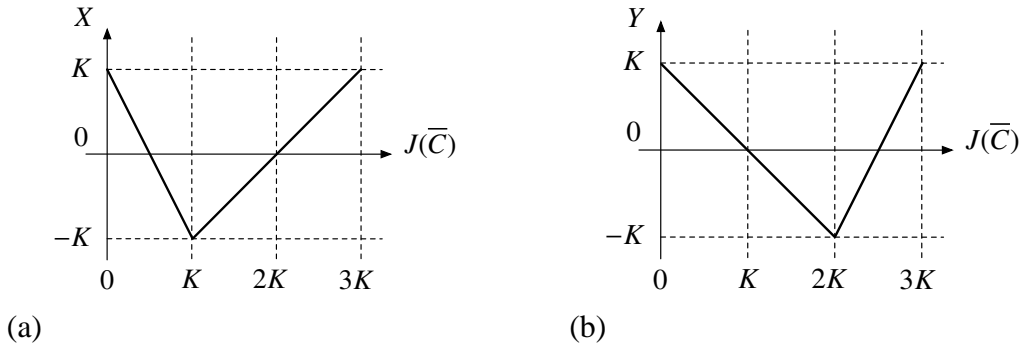


Figure 5. (a): $\pi_1 \circ \eta^{-1} : J(\bar{C}_K) \rightarrow X$. (b): $\pi_2 \circ \eta^{-1} : J(\bar{C}_K) \rightarrow Y$.

arbitrary $u_0 \in J(\bar{C}_K)$ gives the general solution to eq. (2.8).

It is possible to express $\pi_1 \circ \eta^{-1}$ and $\pi_2 \circ \eta^{-1}$ by using the ultradiscrete theta function $\Theta(u; \theta)$ defined by [16, 20, 26, 32, 33, 42]

$$\Theta(u; \theta) = -\theta \left\{ \left((u) - \frac{1}{2} \right) \right\}^2, \quad ((u)) = u - \text{Floor}(u). \quad (2.29)$$

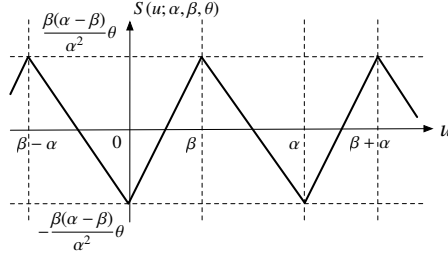


Figure 6. Graph of $S(u; \alpha, \beta, \theta)$.

For this purpose, we introduce a piecewise linear periodic function $S(u; \alpha, \beta, \theta)$ by

$$S(u; \alpha, \beta, \theta) = \Theta\left(\frac{u}{\alpha}; \theta\right) - \Theta\left(\frac{u - \beta}{\alpha}; \theta\right), \quad (2.30)$$

which has a period α and amplitude $2\beta(\alpha - \beta)\theta/\alpha^2$ as illustrated in Fig.6. Comparing Fig. 5 with Fig. 6, we have

$$\pi_1 \circ \eta^{-1}(u) = S\left(u - K; 3K, 2K, \frac{9}{2}K\right), \quad \pi_2 \circ \eta^{-1}(u) = S\left(u - 2K; 3K, K, \frac{9}{2}K\right). \quad (2.31)$$

Therefore, we obtain the following proposition:

Proposition 2.3 *For a given initial value $P_0 = (X_0, Y_0)$, the general solution to the map (2.8) is given by*

$$\begin{aligned} X_n &= S\left(2^n u_0 - K; 3K, 2K, \frac{9}{2}K\right), \quad Y_n = S\left(2^n u_0 - 2K; 3K, K, \frac{9}{2}K\right), \\ K &= 3 \max[X_0, Y_0, 0] - X_0 - Y_0, \quad u_0 = \eta(P_0). \end{aligned} \quad (2.32)$$

Fig. 7 shows the orbit of the map (2.8) plotted with 3,000 times iterations. The map has an invariant curve \overline{C}_K given by eq. (2.5), and the figure shows that the curve is filled with the points of the orbit.

3 Duplication map on Hesse cubic curve

3.1 Duplication map

The Hesse cubic curve is a curve in \mathbb{P}^2 given by

$$E_\mu : \quad x^3 + y^3 + 1 = 3\mu xy, \quad (3.1)$$

or in the homogeneous coordinates $[x_0 : x_1 : x_2] = [x : y : 1]$

$$E_\mu : \quad x_0^3 + x_1^3 + x_2^3 = 3\mu x_0 x_1 x_2. \quad (3.2)$$

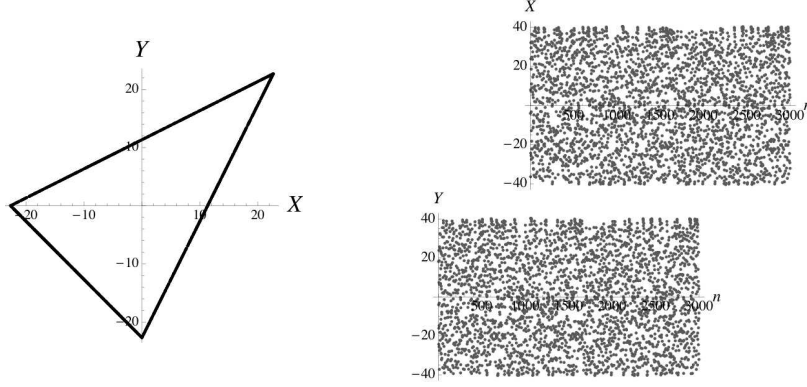


Figure 7. Orbit of the map (2.8) with the initial value $(X_0, Y_0) = (8.56546, 15.6231)$.

The nine inflection points are given by $[1 : -1 : 0]$, $[1 : -\omega : 0]$, $[1 : -\omega^2 : 0]$, $[1 : 0 : -1]$, $[1 : 0 : -\omega]$, $[1 : 0 : -\omega^2]$, $[0 : 1 : -1]$, $[0 : 1 : -\omega]$, $[0 : 1 : -\omega^2]$, where ω is a nontrivial third root of 1. It is known that any non-singular plane cubic curve is projectively equivalent to E_μ (see, e.g. [1]). Moreover, these inflection points are also the base points of the pencil

$$t_0(x_0^3 + x_1^3 + x_2^3) = t_1 x_0 x_1 x_2, \quad [t_0 : t_1] \in \mathbb{P}^1. \quad (3.3)$$

The duplication map is constructed by the standard procedure; for an arbitrary point on $P \in E_\mu$ draw a tangent line, and set the other intersection of the tangent line and E_μ as $P * P$. Taking one of the inflection points as an origin O of addition, the intersection of E_μ and the line connecting $P * P$ and O gives $2P$. Choosing O to be $[1 : -1 : 0]$ among nine inflection points of E_μ , the duplication map $P = (x, y) \mapsto 2P = (\bar{x}, \bar{y})$ is explicitly calculated as (see, for example, [15, 35])

$$\bar{x} = \frac{(1 - x^3)y}{x^3 - y^3}, \quad \bar{y} = \frac{(1 - y^3)x}{y^3 - x^3}, \quad (3.4)$$

or writing the point obtained by the n times applications of the map to (x, y) as (x_n, y_n) , we have

$$x_{n+1} = \frac{(1 - x_n^3)y_n}{x_n^3 - y_n^3}, \quad y_{n+1} = \frac{(1 - y_n^3)x_n}{y_n^3 - x_n^3}. \quad (3.5)$$

By construction, it is obvious that the map (3.5) has the invariant curve E_μ , where μ is the conserved quantity. Fig. 8 shows the orbit of the map (3.5) plotted with 3,000 times iterations. Note that, although the invariant curve has a component in the first quadrant $x, y > 0$ for $\mu > 0$, the real orbit never enters in this quadrant (except for the initial point), which can be verified by a simple consideration; suppose that $x_n > 0$ at some n . Then eq. (3.5) implies that (x_{n-1}, y_{n-1}) must be in the highlighted region of Fig. 9(a). On the other hand, if $y_n > 0$ at some n , (x_{n-1}, y_{n-1}) must be in the highlighted region of Figure 9(b). Since the intersection of the two regions is empty, it is impossible to realize $x_n, y_n > 0$ for any n as long as we start from the real initial value.

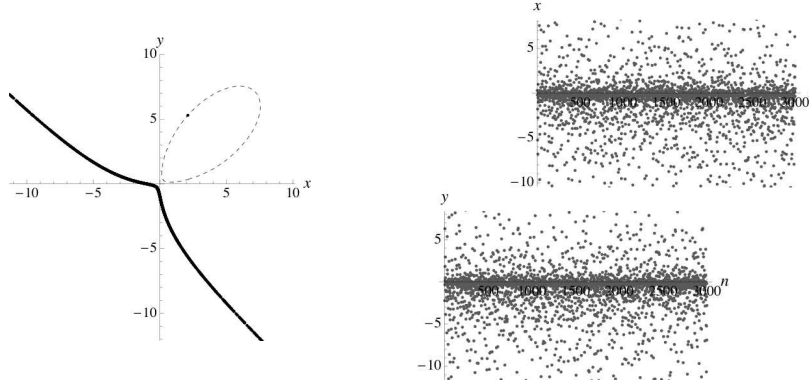


Figure 8. Orbit of the map (3.5) with the initial value $(x_0, y_0) = (2.1, 5.3)$. Dashed line of the left figure is the invariant curve.

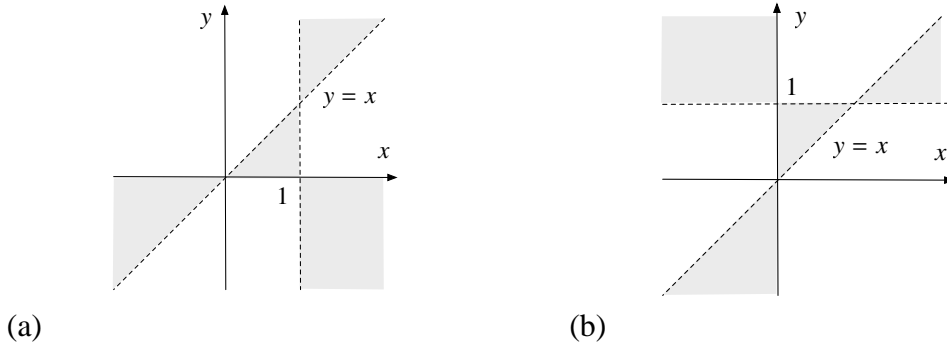


Figure 9. (a): Region of (x_{n-1}, y_{n-1}) for $x_n > 0$. (b): Region of (x_{n-1}, y_{n-1}) for $y_n > 0$.

3.2 General solution

The general solution to the map (3.4) or (3.5) is given in terms of the following theta functions of level 3. Let us introduce the functions $\theta_k(z, \tau)$ ($k = 0, 1, 2$) by

$$\theta_k(z, \tau) = \sum_{n \in \mathbb{Z}} e^{3\pi i(n + \frac{k}{3} - \frac{1}{6})^2 \tau} e^{6\pi i(n + \frac{k}{3} - \frac{1}{6})(z + \frac{1}{2})} = \vartheta_{(\frac{k}{3} - \frac{1}{6}, \frac{3}{2})}(3z, 3\tau), \quad (3.6)$$

where $\vartheta_{(a,b)}(z, \tau)$ is the theta function with characteristic (a, b) defined by

$$\vartheta_{(a,b)}(z, \tau) = \sum_{n \in \mathbb{Z}} e^{\pi i(n+a)^2 \tau + 2\pi i(n+a)(z+b)}, \quad \tau \in \mathcal{H} = \{\text{Im } z > 0, z \in \mathbb{C}\}. \quad (3.7)$$

Proposition 3.1 *The general solution to eq. (3.5) is given by*

$$x_n = \frac{\theta_0(2^n z_0, \tau)}{\theta_2(2^n z_0, \tau)}, \quad y_n = \frac{\theta_1(2^n z_0, \tau)}{\theta_2(2^n z_0, \tau)}, \quad (3.8)$$

where $z_0 \in \mathbb{C}$ is an arbitrary constant.

Proposition 3.1 is a direct consequence of the following proposition:

Proposition 3.2

(1) $\theta_k(z, \tau)$ ($k = 0, 1, 2$) satisfy

$$\theta_0(z, \tau)^3 + \theta_1(z, \tau)^3 + \theta_2(z, \tau)^3 = 3\mu(\tau) \theta_0(z, \tau)\theta_1(z, \tau)\theta_2(z, \tau), \quad \mu(\tau) = -\frac{\varphi'(0, \tau)}{\psi'(0, \tau)}, \quad (3.9)$$

where

$$\varphi(z, \tau) = \frac{\theta_1(z, \tau)}{\theta_0(z, \tau)}, \quad \psi(z, \tau) = \frac{\theta_2(z, \tau)}{\theta_0(z, \tau)}. \quad (3.10)$$

(2) $\theta_k(z, \tau)$ ($k = 0, 1, 2$) satisfy the following duplication formulas:

$$\begin{aligned} \theta_0(0, \tau)^3 \theta_0(2z, \tau) &= \theta_1(z, \tau) \left[\theta_2(z, \tau)^3 - \theta_0(z, \tau)^3 \right], \\ \theta_0(0, \tau)^3 \theta_1(2z, \tau) &= \theta_0(z, \tau) \left[\theta_1(z, \tau)^3 - \theta_2(z, \tau)^3 \right], \\ \theta_0(0, \tau)^3 \theta_2(2z, \tau) &= \theta_2(z, \tau) \left[\theta_0(z, \tau)^3 - \theta_1(z, \tau)^3 \right]. \end{aligned} \quad (3.11)$$

It seems that the above formulas are well known [2], but however, it might be useful for non-experts to give an elementary proof here. In the following, we fix $\tau \in \mathcal{H}$ and write $\theta_k(z, \tau) = \theta_k(z)$.

Lemma 3.3 $\theta_k(z, \tau)$ ($k = 0, 1, 2$) satisfy the following addition formulas:

$$\theta_0(0)^2 \theta_0(x+y) \theta_0(x-y) = \theta_1(x) \theta_2(x) \theta_2(y)^2 - \theta_0(x)^2 \theta_0(y) \theta_1(y), \quad (3.12)$$

$$\theta_0(0)^2 \theta_1(x+y) \theta_0(x-y) = \theta_0(x) \theta_1(x) \theta_1(y)^2 - \theta_2(x)^2 \theta_0(y) \theta_2(y), \quad (3.13)$$

$$\theta_0(0)^2 \theta_2(x+y) \theta_0(x-y) = \theta_0(x) \theta_2(x) \theta_0(y)^2 - \theta_1(x)^2 \theta_1(y) \theta_2(y), \quad (3.14)$$

$$\theta_0(0)^2 \theta_0(x+y) \theta_1(x-y) = \theta_0(x) \theta_1(x) \theta_0(y)^2 - \theta_2(x)^2 \theta_1(y) \theta_2(y), \quad (3.15)$$

$$\theta_0(0)^2 \theta_1(x+y) \theta_1(x-y) = \theta_0(x) \theta_2(x) \theta_2(y)^2 - \theta_1(x)^2 \theta_0(y) \theta_1(y), \quad (3.16)$$

$$\theta_0(0)^2 \theta_2(x+y) \theta_1(x-y) = \theta_1(x) \theta_2(x) \theta_1(y)^2 - \theta_0(x)^2 \theta_0(y) \theta_2(y), \quad (3.17)$$

$$\theta_0(0)^2 \theta_0(x+y) \theta_2(x-y) = \theta_0(x) \theta_2(x) \theta_1(y)^2 - \theta_1(x)^2 \theta_0(y) \theta_2(y), \quad (3.18)$$

$$\theta_0(0)^2 \theta_1(x+y) \theta_2(x-y) = \theta_1(x) \theta_2(x) \theta_0(y)^2 - \theta_0(x)^2 \theta_1(y) \theta_2(y), \quad (3.19)$$

$$\theta_0(0)^2 \theta_2(x+y) \theta_2(x-y) = \theta_0(x) \theta_1(x) \theta_2(y)^2 - \theta_2(x)^2 \theta_0(y) \theta_1(y). \quad (3.20)$$

We give the proof of Lemma 3.3 in the appendix.

Proof of Proposition 3.2.

The duplication formulas (3.11) are obtained by putting $x = y = z$ in eqs. (3.12), (3.13) and (3.14). In order to prove eqs. (3.9) and (3.10), we first note that it follows by definition that

$$\theta_0(-z) = -\theta_1(z), \quad \theta_2(-z) = -\theta_2(z), \quad (3.21)$$

and hence

$$\theta_1(0) = -\theta_0(0), \quad \theta_2(0) = 0. \quad (3.22)$$

From Lemma 3.3, we obtain the addition formulas for $\varphi(z)$ and $\psi(z)$ (see eq. (3.10)) as

$$\varphi(x+y) = \frac{\varphi(x)\varphi(y)^2 - \psi(x)^2\psi(y)}{\varphi(x)\psi(x)\psi(y)^2 - \varphi(y)}, \quad (3.23)$$

$$\varphi(x+y) = \frac{\psi(x)\psi(y)^2 - \varphi(x)^2\varphi(y)}{\varphi(x) - \psi(x)^2\varphi(y)\psi(y)}, \quad (3.24)$$

$$\varphi(x+y) = \frac{\varphi(x)\psi(x) - \varphi(y)\psi(y)}{\psi(x)\varphi(y)^2 - \varphi(x)^2\psi(y)}, \quad (3.25)$$

$$\psi(x+y) = \frac{\psi(x) - \varphi(x)^2\varphi(y)\psi(y)}{\varphi(x)\psi(x)\psi(y)^2 - \varphi(y)}, \quad (3.26)$$

$$\psi(x+y) = \frac{\varphi(x)\psi(x)\varphi(y)^2 - \psi(y)}{\varphi(x) - \psi(x)^2\varphi(y)\psi(y)}, \quad (3.27)$$

$$\psi(x+y) = \frac{\varphi(x)\psi(y)^2 - \psi(x)^2\varphi(y)}{\psi(x)\varphi(y)^2 - \varphi(x)^2\psi(y)}. \quad (3.28)$$

Differentiating eqs. (3.23) and (3.25) by y and putting $y = 0$, we have

$$\varphi'(x) = -\varphi'(0)\varphi(x) - \psi'(0)\psi(x)^2, \quad \varphi'(x) = \frac{\psi'(0) + 2\varphi'(0)\varphi(x)\psi(x) + \psi'(0)\varphi(x)^3}{\psi(x)}, \quad (3.29)$$

respectively. Here we have used

$$\varphi(0) = -1, \quad \psi(0) = 0, \quad (3.30)$$

which follows from eq. (3.22). Equating the right hand sides of the two equations in eq. (3.29), we have

$$1 + \varphi(x)^3 + \psi(x)^3 = -3 \frac{\varphi'(0)}{\psi'(0)} \varphi(x)\psi(x), \quad (3.31)$$

which yields eq. (3.9) by multiplying $\theta_0(z)^3$. This completes the proof. \square

Consider the map

$$\mathbb{C} \ni z \mapsto [\theta_0(z) : \theta_1(z) : \theta_2(z)] \in \mathbb{P}^2(\mathbb{C}). \quad (3.32)$$

From the relations

$$\theta_k(z+1) = -\theta_k(z), \quad \theta_k(z+\tau) = -e^{3\pi i\tau - 6\pi iz} \theta_k(z) \quad (k = 0, 1, 2), \quad (3.33)$$

we see that this induces a map from the complex torus $L_\tau = \mathbb{C}/(\mathbb{Z} + \mathbb{Z}\tau)$ to E_μ , which is known to give an isomorphism $L_\tau \simeq E_\mu$ (see, e.g. [2]). Since $0 \mapsto [1 : -1 : 0]$, the addition formulas (3.12)–(3.20) induce the group structure on E_τ with the origin $[1 : -1 : 0]$. Denoting the addition of two points $[x_0 : x_1 : x_2]$ and $[x'_0 : x'_1 : x'_2]$ as $[x_0 : x_1 : x_2] \oplus [x'_0 : x'_1 : x'_2]$, eqs. (3.12)–(3.20) imply

$$\begin{aligned} & [x_0 : x_1 : x_2] \oplus [x'_0 : x'_1 : x'_2] \\ &= [x_1x_2x_2'^2 - x_0^2x'_0x'_1 : x_0x_1x_1'^2 - x_2^2x'_0x'_2 : x_0x_2x_0'^2 - x_1^2x'_1x'_2] \end{aligned} \quad (3.34)$$

$$= [x_0x_1x_0'^2 - x_2^2x'_1x'_2 : x_0x_2x_2'^2 - x_1^2x'_0x'_1 : x_1x_2x_1'^2 - x_0^2x'_0x'_2] \quad (3.35)$$

$$= [x_0x_2x_1'^2 - x_1^2x'_0x'_2 : x_1x_2x_0'^2 - x_0^2x'_1x'_2 : x_0x_1x_2'^2 - x_2^2x'_0x'_1]. \quad (3.36)$$

In particular, when the two points are equal, the duplication formula is given by

$$2[x_0 : x_1 : x_2] = [x_1(x_2^3 - x_0^3) : x_0(x_1^3 - x_2^3) : x_2(x_0^3 - x_1^3)]. \quad (3.37)$$

Moreover, the inverse of $[x_0 : x_1 : x_2]$ is given by

$$- [x_0 : x_1 : x_2] = [x_1 : x_0 : x_2]. \quad (3.38)$$

We finally remark that μ can be also expressed as follows. Differentiating both equations in eq. (3.10) and putting $z = 0$, we have by using eq. (3.22)

$$\varphi'(0) = 2 \frac{\theta'_0(0)}{\theta_0(0)}, \quad \psi'(0) = \frac{\theta'_2(0)}{\theta_0(0)}, \quad (3.39)$$

which yield

$$\mu(\tau) = -\frac{\varphi'(0)}{\psi'(0)} = -2 \frac{\theta'_0(0)}{\theta'_2(0)}. \quad (3.40)$$

4 Ultradiscretization

So far we have constructed the piecewise linear map (2.8) as the duplication map on the tropical cubic curve C_K , whose general solution is given by eq. (2.32). We have also presented the rational map (3.5) which arises as the duplication map on the Hesse cubic curve E_μ . The general solution of the map is given by eq. (3.8). In this section, we establish a correspondence between the two maps and their general solutions by means of the ultradiscretization.

4.1 Ultradiscretization of map

The key of the ultradiscretization is the following formula:

$$\lim_{\epsilon \rightarrow +0} \epsilon \log \left(e^{\frac{A}{\epsilon}} + e^{\frac{B}{\epsilon}} + \dots \right) = \max[A, B, \dots]. \quad (4.1)$$

Putting

$$x_n = e^{\frac{X_n}{\epsilon}}, \quad y_n = e^{\frac{Y_n}{\epsilon}}, \quad (4.2)$$

we have from eq. (3.5)

$$\begin{aligned} X_{n+1} &= \epsilon \log \left(1 + e^{\frac{3X_n + \epsilon\pi i}{\epsilon}} \right) + Y_n - \epsilon \log \left(e^{\frac{3X_n}{\epsilon}} + e^{\frac{3Y_n + \epsilon\pi i}{\epsilon}} \right), \\ Y_{n+1} &= \epsilon \log \left(1 + e^{\frac{3Y_n + \epsilon\pi i}{\epsilon}} \right) + X_n - \epsilon \log \left(e^{\frac{3X_n}{\epsilon}} + e^{\frac{3Y_n + \epsilon\pi i}{\epsilon}} \right), \end{aligned} \quad (4.3)$$

which yields, in the limit $\epsilon \rightarrow +0$, eq. (2.8):

$$X_{n+1} = \max[0, 3X_n] + Y_n - \max[3X_n, 3Y_n], \quad Y_{n+1} = \max[0, 3Y_n] + X_n - \max[3X_n, 3Y_n]. \quad (4.4)$$

The limit of the invariant curve (3.1) yields \overline{C}_K :

$$\max[0, 3X, 3Y] = X + Y + K, \quad (4.5)$$

by the use of

$$3\mu(\tau) = e^{\frac{K}{\epsilon}}. \quad (4.6)$$

In the above process of the ultradiscretization, we have calculated formally, for example, as

$$\epsilon \log \left(1 - e^{\frac{3X_n}{\epsilon}} \right) = \epsilon \log \left(1 + e^{\frac{3X_n + \epsilon \pi i}{\epsilon}} \right) \longrightarrow \max[0, 3X] \quad (\epsilon \rightarrow +0). \quad (4.7)$$

However, when the original rational map contains the minus signs, such formal calculation sometimes does not give consistent result. This may happen, for example, when we consider the limit of the exact solutions simultaneously, or when we consider the limit of the maps which are representation of certain group or algebra. In both cases, the cancellations caused by the minus signs play a crucial role on the level of rational maps, and the structure of the rational maps is lost because such cancellations do not happen after taking the limit. This problem is sometimes called the minus-sign problem.

Therefore, we usually consider the subtraction-free rational map to apply the ultradiscretization [45, 46, 49]⁵, or we try to transform the map to be subtraction-free if possible [16]. Unfortunately, it seems that the map (3.5) cannot be transformed to be subtraction-free by simple transformations. However, in this case, it is possible to obtain valid ultradiscrete limit of the general solution in spite of the minus-sign problem.

Remark 4.1 The nine inflection points of the Hesse cubic curve correspond to the vertices of the tropical cubic curve C_K in the following manner; consider one of the inflection points $[x_0 : x_1 : x_2] = [1 : -1 : 0] = [e^{\frac{0}{\epsilon}} : e^{\frac{0+i\pi\epsilon}{\epsilon}} : e^{\frac{-\infty}{\epsilon}}]$. Then putting $x_i = e^{\frac{X_i}{\epsilon}}$ ($i = 0, 1, 2$) and taking the limit $\epsilon \rightarrow +0$, we have $[X_0 : X_1 : X_2] = [0 : 0 : -\infty] = [\infty : \infty : 0]$. Note here that on this level equivalence of the homogeneous coordinates is given by $[X_0 : X_1 : X_2] = [X_0 + L : X_1 + L : X_2 + L]$ for any constant L . In the inhomogeneous coordinates, this point corresponds to (∞, ∞) , which is linearly equivalent to the vertex $V_3 = (K, K)$. Similarly, the two points $[1 : -\omega : 0]$, $[1 : -\omega^2 : 0]$ also correspond to V_3 . Furthermore, the triple of points $\{[1 : 0 : -1], [1 : 0 : -\omega], [1 : 0 : -\omega^2]\}$ correspond to $V_2 = (0, -K)$, and the triple $\{[0 : 1 : -1], [0 : 1 : -\omega], [0 : 1 : -\omega^2]\}$ to $V_1 = (-K, 0)$. In other words, three inflection points of the Hesse cubic curve degenerate to each vertex of C_K in the ultradiscrete limit. This explains the reason why the multiplicity of each vertex of C_K is 3 and C_K is not smooth while the Hesse cubic curve is non-singular.

4.2 Ultradiscretization of general solution

In this section, we consider the ultradiscrete limit of the solution. The following is the main result of this paper.

Theorem 4.2 *The general solution (3.8) of the rational map (3.5) reduces to the general solution (2.32) of the piecewise linear map (2.8) by taking the limit $\epsilon \rightarrow +0$ under the parametrization*

$$X_n = e^{\frac{u_n}{\epsilon}}, \quad Y_n = e^{\frac{v_n}{\epsilon}}, \quad \frac{\tau}{\tau + \frac{1}{3}} = -\frac{9K}{2\pi i \epsilon}, \quad z_0 = \frac{u_0}{9K} \left(1 - \frac{2\pi i \epsilon}{9K} \right), \quad u_0 \in \mathbb{R}, \quad K > 0. \quad (4.8)$$

⁵It should be remarked that the term “tropical” has been used differently in the communities of geometry and integrable systems [18]. In the former community it has been used to mean piecewise linear objects, while in the latter subtraction-free rational maps. In the latter community the terms “crystal” or “ultradiscrete” have been used for piecewise linear objects. Therefore, it sometimes happens that the term “tropicalization” can be used with opposite meanings.

The ultradiscrete limit of the theta function can be realized by taking $\text{Im } \tau \rightarrow 0$, however, the limit of the real part of τ should be carefully chosen in order to obtain consistent result [32]. For choosing the limit of real part of τ , the following observation on the correspondence between the zeros of the theta functions and non-smooth points of $S(u; \alpha, \beta, \theta)$ is crucial.

Observation: The ultradiscrete theta function $\Theta(u; \theta)$ defined by eq. (2.29) is a piecewise quadratic function with the period 1, and has zeros at $u = n \in \mathbb{Z}$. $\Theta(u; \theta)$ can be obtained from $\vartheta_0(z; \tau) = \vartheta_{(0, \frac{1}{2})}(z; \tau)$ by taking the limit $\tau \rightarrow 0$ [32]. Since the zeros of $\vartheta_0(z; \tau)$ are located at $z = (m + \frac{1}{2})\tau + n$ ($m, n \in \mathbb{Z}$), the real zeros of $\vartheta_0(z; \tau)$ survive under the limit, giving the zeros of $\Theta(u; \theta)$ at $u = n$. From the definition of S given in eq. (2.30) and Fig.6, it is easy to see that the valleys at $u = n\alpha$ and the peaks at $u = \beta + n\alpha$ ($n \in \mathbb{Z}$) of S correspond to the zeros of $\Theta(\frac{u}{\alpha}; \theta)$ and $\Theta(\frac{u-\beta}{\alpha}; \theta)$, respectively, as illustrated in Fig.10. In other words, valleys and peaks of the ultradiscrete elliptic function S arise from the zeros and poles of the corresponding elliptic function, respectively. Now, noticing

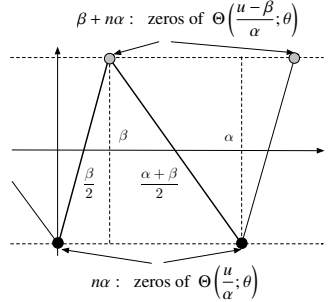


Figure 10. Zigzag pattern of $S(u; \alpha, \beta, \theta) = \Theta(\frac{u}{\alpha}; \theta) - \Theta(\frac{u-\beta}{\alpha}; \theta)$ and the zeros of $\Theta(\frac{u}{\alpha}; \theta)$, $\Theta(\frac{u-\beta}{\alpha}; \theta)$.

that the zeros of $\vartheta_{(a,b)}(z, \tau)$ are located at $z = (-a + m + \frac{1}{2})\tau + (-b + n + \frac{1}{2})$ ($m, n \in \mathbb{Z}$), the zeros of $\theta_k(z, \tau)$ ($k = 0, 1, 2$) are given by

$$\begin{aligned} \theta_0(z, \tau) : \quad z &= \left(m + \frac{2}{3}\right)\tau + \frac{1}{3}(n-1), \\ \theta_1(z, \tau) : \quad z &= \left(m + \frac{1}{3}\right)\tau + \frac{1}{3}(n-1), \\ \theta_2(z, \tau) : \quad z &= m\tau + \frac{1}{3}(n-1), \end{aligned}$$

respectively. It is obvious that the zeros and poles of $x_n = \frac{\theta_0(z, \tau)}{\theta_2(z, \tau)}$ and $y_n = \frac{\theta_1(z, \tau)}{\theta_2(z, \tau)}$ cancel each other, respectively, in the limit $\tau \rightarrow 0$, which yields trivial result. Let us choose $\tau \rightarrow -\frac{1}{3}$. Then the zeros of $\theta_i(z, \tau)$ ($i = 0, 1, 2$) become

$$\begin{aligned} \theta_0(z, \tau) : \quad z &= \frac{\mathbb{Z}}{3} - \frac{2}{9} = \frac{\mathbb{Z}}{3} + \frac{1}{9}, \\ \theta_1(z, \tau) : \quad z &= \frac{\mathbb{Z}}{3} - \frac{1}{9} = \frac{\mathbb{Z}}{3} + \frac{2}{9}, \\ \theta_2(z, \tau) : \quad z &= \frac{\mathbb{Z}}{3}, \end{aligned}$$

respectively, which give the zigzag patterns in the limit as illustrated in Fig.11. These patterns would coincide with the those in Fig.5 after an appropriate scaling.

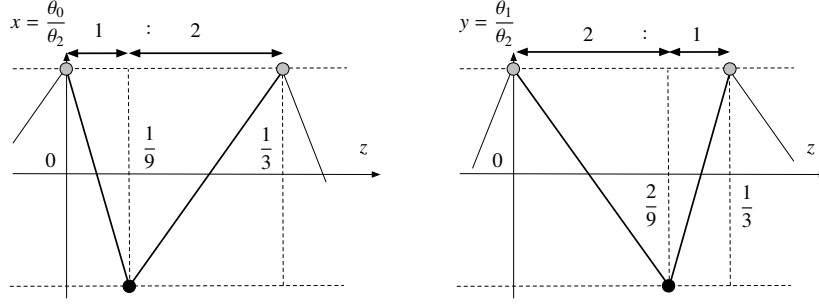


Figure 11. Zigzag patterns obtained by the limit $\tau \rightarrow -\frac{1}{3}$.

Before proceeding to the proof of the Theorem 4.2, we prepare the modular transformation of the theta function, which is useful in taking the limit of τ .

Proposition 4.3 [9, 28]

$$\vartheta_{\sigma \cdot m}(\sigma \cdot z, \sigma \cdot \tau) = e^{\pi i(\sigma \cdot z)cz} (c\tau + d)^{\frac{1}{2}} \kappa(\sigma) e^{2\pi i\phi_m(\sigma)} \vartheta_m(z, \tau), \quad (4.9)$$

where

$$\left\{ \begin{array}{l} m = (m_1, m_2), \quad \sigma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}_2(\mathbb{Z}), \\ \sigma \cdot m = m\sigma^{-1} + \frac{1}{2}(cd, ab), \quad \sigma \cdot \tau = \frac{a\tau + b}{c\tau + d}, \quad \sigma \cdot z = \frac{z}{c\tau + d}, \\ \phi_m(\sigma) = -\frac{1}{2} [bdm_1^2 + acm_2^2 - 2bcm_1m_2 - ab(dm_1 - cm_2)], \\ \kappa(\sigma) : \text{an eighth root of 1 depending only on } \sigma. \end{array} \right. \quad (4.10)$$

Remark 4.4 Explicit expression of $\kappa(\sigma)$ is given by [8]

$$\kappa(\sigma) = \begin{cases} e^{\pi i(\frac{abcd}{2} + \frac{acd^2}{4} - \frac{c}{4})} \left(\frac{a}{|c|} \right), & c : \text{odd} \\ \left(\frac{c}{|d|} \right) (-1)^{(\text{sgn}(c)-1)(\text{sgn}(d)-1)/4} e^{\frac{\pi i}{4}(d-1)}, & c : \text{even} \end{cases}$$

where $\left(\frac{a}{p} \right)$ is the Legendre (Jacobi) symbol for the quadratic residue. In particular, $\left(\frac{a}{1} \right) = 1$.

Proof of Theorem 4.2. The first key of the proof is to apply the modular transformation on $\theta_k(z, \tau) = \vartheta_{(\frac{k}{3} - \frac{1}{6}, \frac{3}{2})}(3z, 3\tau)$ ($k = 0, 1, 2$) specified by

$$\sigma = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}. \quad (4.11)$$

From

$$\sigma \cdot m = \left(\frac{k}{3} - \frac{7}{6}, \frac{3}{2} \right), \quad \phi_m(\sigma) = -\frac{9}{8}, \quad \kappa(\sigma) = 1, \quad (4.12)$$

we have

$$\theta_k(z, \tau) = \vartheta_{(\frac{k}{3}-\frac{1}{6}, \frac{3}{2})}(3z, 3\tau) = e^{-\frac{3\pi i z^2}{\tau+\frac{1}{3}}} (3\tau+1)^{-\frac{1}{2}} e^{\frac{1}{4}\pi i} \vartheta_{(\frac{k}{3}-\frac{7}{6}, \frac{3}{2})}\left(\frac{z}{\tau+\frac{1}{3}}, \frac{\tau}{\tau+\frac{1}{3}}\right). \quad (4.13)$$

We put

$$\frac{\tau}{\tau+\frac{1}{3}} = -\frac{\theta}{i\pi\epsilon}, \quad \theta > 0, \quad (4.14)$$

and take the limit of $\epsilon \rightarrow +0$ which corresponds to $\tau \rightarrow -\frac{1}{3}$. Noticing $\frac{z}{\tau+\frac{1}{3}} = 3\left(\frac{\theta}{i\pi\epsilon} + 1\right)z$, we have

$$\vartheta_{(\frac{k}{3}-\frac{7}{6}, \frac{3}{2})}\left(\frac{z}{\tau+\frac{1}{3}}, \frac{\tau}{\tau+\frac{1}{3}}\right) = \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}(n+\frac{k}{3}-\frac{7}{6})^2 + \frac{6\theta}{\epsilon}(n+\frac{k}{3}-\frac{7}{6})z} e^{6\pi i(n+\frac{k}{3}-\frac{7}{6})(z+\frac{1}{2})}. \quad (4.15)$$

The second key is to use the freedom of the imaginary part of $z \in \mathbb{C}$. Putting

$$z = \frac{u}{9K} + iv, \quad K, u, v \in \mathbb{R}, \quad (4.16)$$

eq. (4.15) is rewritten as

$$\begin{aligned} \vartheta_{(\frac{k}{3}-\frac{7}{6}, \frac{3}{2})}\left(\frac{z}{\tau+\frac{1}{3}}, \frac{\tau}{\tau+\frac{1}{3}}\right) &= \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}(n+\frac{k}{3}-\frac{7}{6})^2 + \frac{6\theta}{\epsilon}(n+\frac{k}{3}-\frac{7}{6})(\frac{u}{9K}+iv)} e^{6\pi i(n+\frac{k}{3}-\frac{7}{6})(\frac{u}{9K}+iv+\frac{1}{2})} \\ &= e^{\frac{\theta}{9K^2\epsilon}u^2} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}[\frac{u}{3K}-n-\frac{k}{3}+\frac{7}{6}]^2 - 6\pi(n+\frac{k}{3}-\frac{7}{6})v} e^{6\pi i(n+\frac{k}{3}-\frac{7}{6})[\frac{\theta}{\pi\epsilon}v+\frac{u}{9K}+\frac{1}{2}]}. \end{aligned} \quad (4.17)$$

If u and v satisfy

$$\frac{\theta}{\pi\epsilon}v + \frac{u}{9K} = 0, \quad (4.18)$$

then eq. (4.17) is simplified as

$$\begin{aligned} \vartheta_{(\frac{k}{3}-\frac{7}{6}, \frac{3}{2})}\left(\frac{z}{\tau+\frac{1}{3}}, \frac{\tau}{\tau+\frac{1}{3}}\right) &= e^{\frac{\theta}{9K^2\epsilon}u^2} e^{\pi i(k-\frac{7}{2})} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}[\frac{u}{3K}-n-\frac{k}{3}+\frac{7}{6}]^2 - 6\pi(n+\frac{k}{3}-\frac{7}{6})v} e^{3\pi i n} \\ &= e^{\frac{\theta}{9K^2\epsilon}u^2} e^{\pi i(k-\frac{7}{2})} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}[\frac{u-K(k+1)}{3K}-(n-2)-\frac{1}{2}]^2 + (n+\frac{k}{3}-\frac{7}{6})\frac{2\pi^2\epsilon}{3K\theta}u} e^{3\pi i n}. \end{aligned}$$

Therefore, asymptotic behaviors of x_n and y_n as $\epsilon \sim +0$ are given by

$$\begin{aligned} x_n = \frac{\theta_0(z, \tau)}{\theta_2(z, \tau)} &\sim \frac{\sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}[\frac{u-K}{3K}-(n-2)-\frac{1}{2}]^2} e^{3\pi i n}}{e^{2\pi i} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}[\frac{u-3K}{3K}-(n-2)-\frac{1}{2}]^2} e^{3\pi i n}} \sim e^{(n_0+n_2)\pi i} \frac{e^{-\frac{\theta}{\epsilon}[(\frac{u-K}{3K})-\frac{1}{2}]^2}}{e^{-\frac{\theta}{\epsilon}[(\frac{u-3K}{3K})-\frac{1}{2}]^2}}, \\ y_n = \frac{\theta_1(z, \tau)}{\theta_2(z, \tau)} &\sim \frac{e^{\pi i} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}[\frac{u-2K}{3K}-(n-2)-\frac{1}{2}]^2} e^{3\pi i n}}{e^{2\pi i} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}[\frac{u-3K}{3K}-(n-2)-\frac{1}{2}]^2} e^{3\pi i n}} \sim e^{(n_1+n_2+1)\pi i} \frac{e^{-\frac{\theta}{\epsilon}[(\frac{u-2K}{3K})-\frac{1}{2}]^2}}{e^{-\frac{\theta}{\epsilon}[(\frac{u-3K}{3K})-\frac{1}{2}]^2}}, \end{aligned} \quad (4.19)$$

respectively, where

$$n_0 = \text{Floor} \left[\frac{u-K}{3K} \right] + 2, \quad n_1 = \text{Floor} \left[\frac{u-2K}{3K} \right] + 2, \quad n_2 = \text{Floor} \left[\frac{u-3K}{3K} \right] + 2. \quad (4.20)$$

Here, we note that z and u are understood as $2^n z_0$ and $2^n u_0$, respectively.

In order to obtain the final result, the remaining task is to relate the parameters θ with K in the limit $\epsilon \rightarrow +0$. This can be done by considering the limit of the conserved quantity $\mu(\tau)$ given by eq. (3.9) or eq. (3.40). Noticing eq. (3.40), we differentiate $\theta_0(z, \tau)$ and $\theta_2(z, \tau)$ by z after applying the modular transformation. Then $\theta'_0(0, \tau)$ and $\theta'_1(0, \tau)$ can be calculated by using eqs. (4.13) and (4.15) as

$$\begin{aligned} \theta'_0(0, \tau) &= \frac{\partial}{\partial z} \vartheta_{(-\frac{1}{6}, \frac{3}{2})}(3z, 3\tau) \Big|_{z=0} \\ &= \frac{\partial}{\partial z} e^{-\pi i(1+\frac{\theta}{i\pi\epsilon})z^2} \left(1 + \frac{\theta}{i\pi\epsilon}\right)^{\frac{1}{2}} e^{\frac{1}{4}\pi i} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}(n-\frac{7}{6})^2 + \frac{6\theta}{\epsilon}(n-\frac{7}{6})z} e^{6\pi i(n-\frac{7}{6})(z+\frac{1}{2})} \Big|_{z=0} \\ &= \left(1 + \frac{\theta}{i\pi\epsilon}\right)^{\frac{1}{2}} e^{\frac{3}{4}\pi i} \sum_{n \in \mathbb{Z}} \left[6\left(\pi i + \frac{\theta}{\epsilon}\right)\left(n - \frac{7}{6}\right)\right] e^{-\frac{\theta}{\epsilon}(n-\frac{7}{6})^2 + 3n\pi i}, \end{aligned}$$

$$\begin{aligned} \theta'_2(0, \tau) &= \frac{\partial}{\partial z} \vartheta_{(\frac{1}{2}, \frac{3}{2})}(3z, 3\tau) \Big|_{z=0} \\ &= \frac{\partial}{\partial z} e^{-\pi i(1+\frac{\theta}{i\pi\epsilon})z^2} \left(1 + \frac{\theta}{i\pi\epsilon}\right)^{\frac{1}{2}} e^{\frac{1}{4}\pi i} \sum_{n \in \mathbb{Z}} e^{-\frac{\theta}{\epsilon}(n-\frac{1}{2})^2 + \frac{6\theta}{\epsilon}(n-\frac{1}{2})z} e^{6\pi i(n-\frac{1}{2})(z+\frac{1}{2})} \Big|_{z=0} \\ &= \left(1 + \frac{\theta}{i\pi\epsilon}\right)^{\frac{1}{2}} e^{\frac{3}{4}\pi i} \sum_{n \in \mathbb{Z}} \left[6\left(\pi i + \frac{\theta}{\epsilon}\right)\left(n - \frac{1}{2}\right)\right] e^{-\frac{\theta}{\epsilon}(n-\frac{1}{2})^2 + 3n\pi i}, \end{aligned}$$

respectively, which imply

$$3\mu = -6 \frac{\theta'_0(0, \tau)}{\theta'_2(0, \tau)} = -6 \frac{e^{\frac{3}{4}\pi i} \sum_{n \in \mathbb{Z}} \left(n - \frac{7}{6}\right) e^{-\frac{\theta}{\epsilon}(n-\frac{7}{6})^2 + 3n\pi i}}{e^{\frac{3}{4}\pi i} \sum_{n \in \mathbb{Z}} \left(n - \frac{1}{2}\right) e^{-\frac{\theta}{\epsilon}(n-\frac{1}{2})^2 + 3n\pi i}} \sim -6 \frac{\left(-\frac{1}{6}\right) e^{-\frac{\theta}{36\epsilon} + 3\pi i}}{-\frac{1}{2} e^{-\frac{\theta}{4\epsilon}} + \frac{1}{2} e^{-\frac{\theta}{4\epsilon} + 3\pi i}} = e^{\frac{2\theta}{9\epsilon}},$$

as $\epsilon \rightarrow +0$. Accordingly, from eq. (4.6) we may put consistently as

$$\theta = \frac{9}{2}K. \quad (4.21)$$

Let us set $x_n = e^{\frac{x_n}{\epsilon}}$ and $y_n = e^{\frac{y_n}{\epsilon}}$ in eq. (4.19). Then the complex factors in eq. (4.19) disappear in the limit of $\epsilon \rightarrow 0$ and we finally obtain by using eq. (4.21)

$$\begin{aligned} X_n &= -\frac{9K}{2} \left[\left(\left(\frac{u-K}{3K} \right) \right) - \frac{1}{2} \right]^2 + \frac{9K}{2} \left[\left(\left(\frac{u-3K}{3K} \right) \right) - \frac{1}{2} \right]^2, \\ Y_n &= -\frac{9K}{2} \left[\left(\left(\frac{u-2K}{3K} \right) \right) - \frac{1}{2} \right]^2 + \frac{9K}{2} \left[\left(\left(\frac{u-3K}{3K} \right) \right) - \frac{1}{2} \right]^2, \end{aligned} \quad (4.22)$$

which is equivalent to eq. (2.32). This completes the proof. \square

We finally remark that the choice of parametrization (4.8) can be also justified by the following observation. The asymptotic formula (4.19) shows that (x_n, y_n) is in \mathbb{R}^2 and that the quadrant of (x_n, y_n) changes according to the value of $((\frac{u}{3K}))$ as described in Table 1. Note that (x_n, y_n) never enters the first quadrant. It implies that qualitative behavior of the real orbit of the map (2.8) discussed in Section 3 is preserved under the limiting process.

$((\frac{u}{3K}))$	n_0	n_1	n_2	$n_0 + n_2$	$n_1 + n_2 + 1$	(x_n, y_n)
$[\frac{2}{3}, 1)$	N	N	$N - 1$	$2N - 1$	$2N$	$(-, +)$
$[\frac{1}{3}, \frac{2}{3})$	N	$N - 1$	$N - 1$	$2N - 1$	$2N - 1$	$(-, -)$
$[0, \frac{1}{3})$	$N - 1$	$N - 1$	$N - 1$	$2N - 2$	$2N - 1$	$(+, -)$

Table 1. Quadrant of (x_n, y_n) for $\epsilon \sim +0$, where $N = \text{Floor}((\frac{u}{3K})) + 2$.

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A Proof of Lemma 3.3

In this appendix, we give a proof of Lemma 3.3. Besides the cases $k = 0, 1, 2$ we also use the cases $k = \frac{1}{2}, \frac{3}{2}, \frac{5}{2}$ as well. Note that $\theta_{k+3}(z, \tau) = \theta_k(z, \tau)$.

First, we remark that $\theta_{\frac{1}{2}}(z, \tau) = \vartheta_{(0, \frac{3}{2})}(3z, 3\tau)$ and $\theta_2(z, \tau) = \vartheta_{(\frac{1}{2}, \frac{3}{2})}(3z, 3\tau)$ are $\vartheta(3z, 3\tau)$ and $\vartheta_1(3z, 3\tau)$ of Jacobi's notation, respectively. Let us start from the eq. (A)-(4) in [14]:

$$\begin{aligned} & \theta_{\frac{1}{2}}(w)\theta_{\frac{1}{2}}(x)\theta_{\frac{1}{2}}(y)\theta_{\frac{1}{2}}(z) - \theta_2(w)\theta_2(x)\theta_2(y)\theta_2(z) \\ &= \theta_{\frac{1}{2}}(w')\theta_{\frac{1}{2}}(x')\theta_{\frac{1}{2}}(y')\theta_{\frac{1}{2}}(z') - \theta_2(w')\theta_2(x')\theta_2(y')\theta_2(z'), \end{aligned} \quad (\text{A.1})$$

where

$$w' = \frac{w+x+y+z}{2}, \quad x' = \frac{w+x-y-z}{2}, \quad y' = \frac{w-x+y-z}{2}, \quad z' = \frac{w-x-y+z}{2}. \quad (\text{A.2})$$

Replacing w as $w \rightarrow w + \frac{\tau}{3}$, we have $w' \rightarrow w' + \frac{\tau}{6}$, $x' \rightarrow x' + \frac{\tau}{6}$, $y' \rightarrow y' + \frac{\tau}{6}$ and $z' \rightarrow z' + \frac{\tau}{6}$. By using the formula

$$\theta_k\left(z + \frac{\tau}{6}\right) = e^{-\frac{\pi i}{2}} e^{-\frac{\pi i \tau}{12} - \pi i z} \theta_{k+\frac{1}{2}}(z), \quad \theta_k\left(z + \frac{\tau}{3}\right) = e^{-\pi i} e^{-\frac{\pi i \tau}{3} - 2\pi i z} \theta_{k+1}(z), \quad (\text{A.3})$$

which easily follows by definition, we obtain

$$\begin{aligned} & -\theta_{\frac{3}{2}}(w)\theta_{\frac{1}{2}}(x)\theta_{\frac{1}{2}}(y)\theta_{\frac{1}{2}}(z) + \theta_0(w)\theta_2(x)\theta_2(y)\theta_2(z) \\ &= \theta_1(w')\theta_1(x')\theta_1(y')\theta_1(z') - \theta_{\frac{5}{2}}(w')\theta_{\frac{3}{2}}(x')\theta_{\frac{3}{2}}(y')\theta_{\frac{3}{2}}(z'). \end{aligned} \quad (\text{A.4})$$

Replacing further as $w \rightarrow w + \frac{\tau}{3}$, $x \rightarrow x + \frac{\tau}{3}$, $y \rightarrow y + \frac{\tau}{3}$ and $z \rightarrow z + \frac{\tau}{3}$, we see that $w' \rightarrow w' + \frac{2\tau}{3}$ and x', y', z' are unchanged. Then we obtain

$$\begin{aligned} & -\theta_{\frac{5}{2}}(w)\theta_{\frac{3}{2}}(x)\theta_{\frac{3}{2}}(y)\theta_{\frac{3}{2}}(z) + \theta_1(w)\theta_0(x)\theta_0(y)\theta_0(z) \\ & = \theta_0(w')\theta_1(x')\theta_1(y')\theta_1(z') - \theta_{\frac{3}{2}}(w')\theta_{\frac{5}{2}}(x')\theta_{\frac{5}{2}}(y')\theta_{\frac{5}{2}}(z'). \end{aligned} \quad (\text{A.5})$$

Application of the same transformation to eq. (A.1) yields

$$\begin{aligned} & \theta_{\frac{3}{2}}(w)\theta_{\frac{3}{2}}(x)\theta_{\frac{3}{2}}(y)\theta_{\frac{3}{2}}(z) - \theta_0(w)\theta_0(x)\theta_0(y)\theta_0(z) \\ & = \theta_{\frac{5}{2}}(w')\theta_{\frac{1}{2}}(x')\theta_{\frac{1}{2}}(y')\theta_{\frac{1}{2}}(z') - \theta_1(w')\theta_2(x')\theta_2(y')\theta_2(z'). \end{aligned} \quad (\text{A.6})$$

We put $w = -(x + y + z)$ in eqs. (A.4) and (A.5). Then $w' = 0$, $x' = -(y + z)$, $y' = -(z + x)$ and $z' = -(x + y)$. By definition it follows that

$$\theta_0(-z) = -\theta_1(z), \quad \theta_{\frac{1}{2}}(-z) = \theta_{\frac{1}{2}}(z), \quad \theta_2(-z) = -\theta_2(z), \quad \theta_{\frac{3}{2}}(-z) = \theta_{\frac{3}{2}}(z), \quad (\text{A.7})$$

and hence

$$\theta_1(0) = -\theta_0(0), \quad \theta_{\frac{5}{2}}(0) = \theta_{\frac{3}{2}}(0), \quad \theta_2(0) = 0. \quad (\text{A.8})$$

Therefore eqs. (A.4) and (A.5) yield

$$\begin{aligned} & -\theta_{\frac{5}{2}}(x + y + z)\theta_{\frac{1}{2}}(x)\theta_{\frac{1}{2}}(y)\theta_{\frac{1}{2}}(z) - \theta_1(x + y + z)\theta_2(x)\theta_2(y)\theta_2(z) \\ & = \theta_1(0)\theta_0(y + z)\theta_0(z + x)\theta_0(x + y) - \theta_{\frac{3}{2}}(0)\theta_{\frac{3}{2}}(y + z)\theta_{\frac{3}{2}}(z + x)\theta_{\frac{3}{2}}(x + y), \end{aligned} \quad (\text{A.9})$$

$$\begin{aligned} & \theta_{\frac{3}{2}}(x + y + z)\theta_{\frac{3}{2}}(x)\theta_{\frac{3}{2}}(y)\theta_{\frac{3}{2}}(z) + \theta_0(x + y + z)\theta_0(x)\theta_0(y)\theta_0(z) \\ & = -\theta_0(0)\theta_0(y + z)\theta_0(z + x)\theta_0(x + y) - \theta_{\frac{3}{2}}(0)\theta_{\frac{3}{2}}(y + z)\theta_{\frac{3}{2}}(z + x)\theta_{\frac{3}{2}}(x + y), \end{aligned} \quad (\text{A.10})$$

respectively. Similarly, putting $w = x + y + z$, we have that $w' = x + y + z$ and x', y', z' are unchanged. Then eq. (A.6) yields

$$\begin{aligned} & \theta_{\frac{3}{2}}(x + y + z)\theta_{\frac{3}{2}}(x)\theta_{\frac{3}{2}}(y)\theta_{\frac{3}{2}}(z) - \theta_0(x + y + z)\theta_0(x)\theta_0(y)\theta_0(z) \\ & = \theta_{\frac{5}{2}}(x + y + z)\theta_{\frac{1}{2}}(x)\theta_{\frac{1}{2}}(y)\theta_{\frac{1}{2}}(z) - \theta_1(x + y + z)\theta_2(x)\theta_2(y)\theta_2(z). \end{aligned} \quad (\text{A.11})$$

Then from $-(\text{A.9}) + (\text{A.10}) + (\text{A.11})$ and dividing it by 2, we have

$$\theta_0(0)\theta_0(y + z)\theta_0(z + x)\theta_0(x + y) = \theta_0(x + y + z)\theta_0(x)\theta_0(y)\theta_0(z) - \theta_1(x + y + z)\theta_2(x)\theta_2(y)\theta_2(z), \quad (\text{A.12})$$

which yields eq. (3.12) by putting $z = -y$ in eq. (A.12). Other addition formulas are derived from eq. (3.12). Applying $x \rightarrow x + \frac{\tau}{3}$, $y \rightarrow y + \frac{\tau}{3}$ on eq. (3.12), we have

$$\theta_0(0)^2\theta_1(x + y)\theta_0(x - y) = \theta_0(x)\theta_1(x)\theta_1(y)^2 - \theta_2(x)^2\theta_0(y)\theta_2(y). \quad (\text{A.13})$$

Repeating the same procedure on eq. (A.13), we obtain

$$\theta_0(0)^2\theta_2(x + y)\theta_0(x - y) = \theta_0(x)\theta_2(x)\theta_0(y)^2 - \theta_1(x)^2\theta_1(y)\theta_2(y). \quad (\text{A.14})$$

Exchanging $x \leftrightarrow y$ in eq. (3.12), we have

$$\theta_0(0)^2\theta_0(x + y)\theta_1(x - y) = \theta_0(x)\theta_1(x)\theta_0(y)^2 - \theta_2(x)^2\theta_1(y)\theta_2(y). \quad (\text{A.15})$$

Repeating $x \rightarrow x + \frac{\tau}{3}$, $y \rightarrow y + \frac{\tau}{3}$ on eq. (A.15) twice yield

$$\theta_0(0)^2 \theta_1(x+y) \theta_1(x-y) = \theta_0(x) \theta_2(x) \theta_2(y)^2 - \theta_1(x)^2 \theta_0(y) \theta_1(y), \quad (\text{A.16})$$

$$\theta_0(0)^2 \theta_2(x+y) \theta_1(x-y) = \theta_1(x) \theta_2(x) \theta_1(y)^2 - \theta_0(x)^2 \theta_0(y) \theta_2(y), \quad (\text{A.17})$$

respectively. Applying $x \rightarrow x + \frac{\tau}{3}$ to eq. (A.17), we obtain

$$\theta_0(0)^2 \theta_0(x+y) \theta_2(x-y) = \theta_0(x) \theta_2(x) \theta_1(y)^2 - \theta_1(x)^2 \theta_0(y) \theta_2(y). \quad (\text{A.18})$$

Again, repeating $x \rightarrow x + \frac{\tau}{3}$, $y \rightarrow y + \frac{\tau}{3}$ on eq. (A.15) twice, we have

$$\theta_0(0)^2 \theta_1(x+y) \theta_2(x-y) = \theta_1(x) \theta_2(x) \theta_0(y)^2 - \theta_0(x)^2 \theta_1(y) \theta_2(y), \quad (\text{A.19})$$

$$\theta_0(0)^2 \theta_2(x+y) \theta_2(x-y) = \theta_0(x) \theta_1(x) \theta_2(y)^2 - \theta_2(x)^2 \theta_0(y) \theta_1(y), \quad (\text{A.20})$$

respectively. This completes the proof of Lemma 3.3. \square

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